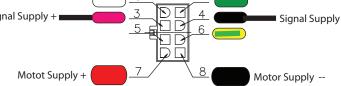


| | Specifications | ZDMJ-1/ | ′GK1 | 3 | |
|-----------------------|-----------------------|------------------------------------|--------|--------------------------|--|
| Model of Motor | ZDMJ-1 | Output shaft and Motor rotation | | Same Direction | |
| Voltage/Frequency | 24VDC | | | | |
| Output Power | 60W | Bearing Type | | Ball Bearing | |
| Rated Current | 4.0A±10% | Gearbox Config. | | Integrated | |
| rated speed | 1800rpm±5% 138.46 O/P | Maximum Allowable Torque | | 0.401 | |
| Rated Torque | 0.32N.m | | | 2.49N.m | |
| No load Speed | 2300rpm±5% 177 O/P | Transimit Effic | ciency | 60% | |
| No Load Current | <1.0A | Noise | | <55dB (L=40cm) | |
| Duty | Cont | Connect Type: Tyco | | 4.2mm PE Series 794954-8 | |
| Insulation resistance | >50M ^Ω | Mates with: Tyco | | 4.2mm PE Series 794953-8 | |
| Hi Voltage Test | 660V/S | | | | |
| In.Class | В | | | | |
| Protection Grade | IP20 | 1 | | | |
| Using temperature | −10°C~+40°C | 1 | | | |
| Gearbox | GK13 13:1 Reduction | 1 | | | |

| Socket & Wire Legend | | | | | | | | |
|----------------------|------------|---------------------|--------------------|---|---------------------|--------|-----------------------|--|
| 1 white | 2 green | 3red | 4black | 5 | 6 green 6 yellow | | 8blackUL1015 20AWG | |
| out Vccw | out Vcw | signal V+(5~24v) | signal V-(5~24) | / | GND | 24VDC+ | 24VDC- | |
| | | | _ 1 | | 2 _ | | | |
| anal Sup | nlv + | | 3 | 0 | $\frac{2}{4}$ | | Signal Supr | |



Notes:

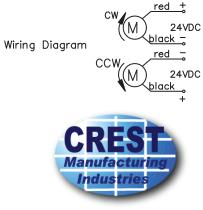
1. Connector

The supplied connector may fit directly into some door operating mechanisms. (See Plug Type) If it does not suit your particular application, cut it off and connect the wires directly to your circuit.

2. Speed & Direction Sensing

These signals do not need to be used to operate this gearmotor. Simply connecting RED & BLACK to a 24 VDC power source will operate the gearmotor. (See Note 3) The signal output is two square waves of the amplitude determined by your selected signal voltage supply (V+ selected between 5 & 24 VDC) in quadrature (90 Degrees phase shifted).

3. Basic Motor Operating Connection



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