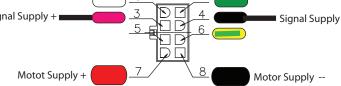


	Specifications	ZDMJ-1/	′GK1	3	
Model of Motor	ZDMJ-1	Output shaft and Motor rotation		Same Direction	
Voltage/Frequency	24VDC				
Output Power	60W	Bearing Type		Ball Bearing	
Rated Current	4.0A±10%	Gearbox Config.		Integrated	
rated speed	1800rpm±5% 138.46 O/P	Maximum Allowable Torque		0.401	
Rated Torque	0.32N.m			2.49N.m	
No load Speed	2300rpm±5% 177 O/P	Transimit Effic	ciency	60%	
No Load Current	<1.0A	Noise		<55dB (L=40cm)	
Duty	Cont	Connect Type: Tyco		4.2mm PE Series 794954-8	
Insulation resistance	>50M ^Ω	Mates with: Tyco		4.2mm PE Series 794953-8	
Hi Voltage Test	660V/S				
In.Class	В				
Protection Grade	IP20	1			
Using temperature	−10°C~+40°C	1			
Gearbox	GK13 13:1 Reduction	1			

Socket & Wire Legend								
1 white	2 green	3red	4black	5	6 green 6 yellow		8blackUL1015 20AWG	
out Vccw	out Vcw	signal V+(5~24v)	signal V-(5~24)	/	GND	24VDC+	24VDC-	
			_ 1		2 _			
anal Sup	nlv +		3	0	$\frac{2}{4}$		Signal Supr	



Notes:

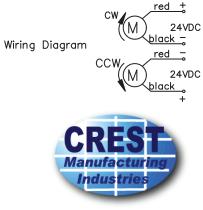
1. Connector

The supplied connector may fit directly into some door operating mechanisms. (See Plug Type) If it does not suit your particular application, cut it off and connect the wires directly to your circuit.

2. Speed & Direction Sensing

These signals do not need to be used to operate this gearmotor. Simply connecting RED & BLACK to a 24 VDC power source will operate the gearmotor. (See Note 3) The signal output is two square waves of the amplitude determined by your selected signal voltage supply (V+ selected between 5 & 24 VDC) in quadrature (90 Degrees phase shifted).

3. Basic Motor Operating Connection



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